

# Toward space-time parallel simulations of phase-field models

Oktober 9, 2018 | Ruth Schöbel & Robert Speck Jülich Supercomputing Centre, Forschungszentrum Jülich GmbH



# The consortium



Uwe Glatzel Applications



Carsten Gräser Numerics



Oliver Sander Numerics



Universität Stuttgart

Marc-Andre Keip Applications



Robert Speck HPC



Jiri Kraus HPC



# **BMBF-Project ParaPhase**

High-order space-time parallel phase-field simulations

- interface problems can be modeled with phase-field equations
- wide range of applications, e.g. fracture propagation in ceramics, drying soil etc.
- some key phenomena only emerge when the domain is large and simulation time long enough
- significant computing cost  $\Rightarrow$  parallelism in space and time



Figure: Modeling of fracture propagation in dry soil



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# A not so simple toy problem (in space)



Model problem:

 $\begin{aligned} -\Delta u &= f \quad \text{ on } \Omega := [0,1]^2 \\ u &\leq u_+ \quad \text{ on } \Omega \\ u &= g \quad \text{ on } \partial \Omega \end{aligned}$ 

Our approach: multigrid

- very efficient (mostly)
- supported by theory
- parallelizable



# Parallel multigrid with DUNE

### DUNE = Distributed and Unified Numerics Environment

- modular C++ library
- easy implementation of methods like Finite Elements
- slim interfaces, HPC-ready, easy to extend





# Strong scaling for obstacle problem



- Parallel version of TNNMG for obstacle problem
- Sequential solver for coarse grid problem
- Number of iterations increases from 20 to 38





#### The TNNMG algorithm



## Pre-smoothing: projected Gauss-Seidel

- Linear multigrid step for reduced problem
- Project on K<sub>alg</sub>
- Line search to ensure monotonicity



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# Application: Notched domain under tension

#### A Boundary Value Problem



- Single-edge-notched domain under tensile loading
- Deformation by a linear increasing non-homogeneous Dirichlet boundary condition at the top
- TNNMG is much faster!

#### Ruth Schöbel & Robert Speck



#### Further improvements: High-Order DG for Phase-Fields Phase-Field and its Discretization

- Problems typically involve smooth and non-smooth parts
- adaptively refine grid to better resolve non-smooth areas
- for smooth parts, employ ansatz functions of higher order



- for smooth parts, employ ansatz functions of higher order
- Discontinuous Galerkin for more flexibility and data-locality
- hybrid use of classical matrix-based and matrix-free methods



# Adding time

 $\textbf{Complexity} \ + = 1$ 

What if our problems are time-dependent?

- example: Allen-Cahn or Cahn-Hilliard equations: diffuse interface model for phase transition and separation phenomena
- TNNMG allows semi- or fully implicit time-stepping with provable convergence
- parallel TNNMG = parallelization in space for time-dependent phase-field problems



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Are we done, then?





- Spatial parallelization reduces runtime per time-step
- Strong scaling saturates eventually because of communication
- Costs for more time-steps are not mitigated





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- Strong scaling saturates eventually because of communication
- Costs for more time-steps are not mitigated
- $\rightarrow$  Can we compute multiple time-steps simultaneously?



## A quick algebraic introduction to PFASST Basic building block: spectral deferred corrections (SDC)

Consider the Picard form of an initial value problem on  $[T_n, T_{n+1}]$ 

$$u(t) = u_0 + \int_{T_n}^t f(u(s)) ds,$$

discretized using spectral quadrature rules with nodes  $t_m$ :

$$u_m = u_0 + \Delta t Q F(u) \approx u_0 + \int_{T_l}^{t_m} f(u(s)) ds,$$

then SDC methods can be seen as (approximative) Gauss-Seidel iteration to solve this collocation problem for all  $u_m$ .



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 $(I - \Delta t Q F)(\vec{u}) = \vec{u}_0$ 

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 $\Rightarrow$  Use this for block smoothing in space-time multigrid = PFASST



# A quick algebraic introduction to PFASST

Parallel Full Approximation Scheme in Space and Time

We now glue *L* time-steps together, using *N* to transfer information from step *I* to step I + 1. We get:

$$\begin{pmatrix} I - \Delta t QF \\ -N & I - \Delta t QF \\ \vdots \\ \ddots & \ddots \\ -N & I - \Delta t QF \end{pmatrix} \begin{pmatrix} \vec{u}_1 \\ \vec{u}_2 \\ \vdots \\ \vec{u}_L \end{pmatrix} = \begin{pmatrix} \vec{u}_0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

### PFASST:

- use (linear/FAS) multigrid to solve this system iteratively
- fine-level smoother: parallel block Jacobi with SDC in the blocks
- coarse-level: serial block Gauß-Seidel with SDC in the blocks







































































# Gray-Scott simulation with DUNE and PFASST

$$u_t = D_u \Delta u - uv^2 + F(1 - u)$$
  
$$v_t = D_v \Delta v + uv^2 - (F + K)v$$



512<sup>2</sup> elements, 
$$dt = 2$$
, tol =  $10^{-14}$ ,  $D_u = 10^{-4}$ ,  $D_v = 10^{-5}$ ,  $F = 0.0367$ ,  $K = 0.0649$   
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## Three takeaways



Parallel TNNMG method provides reliable and efficient solver for phase-field problems

Parallel-in-Time integration (PinT) can help to extend prevailing scaling limits





Space-time parallelization within **DUNE** leaves us with a ton of things to play with



# The PinT Community

To learn more about PinT check out the website

www.parallelintime.org

and/or join one of the PinT Workshops, e.g.

## 8th Workshop on Parallel-in-Time Integration

- May 20-24, 2019
- ZIF Bielefeld, Germany
- organized by Daniel Ruprecht, Sebastian Schöps and Robert Speck



Also, there is a mailing list, join by writing to

parallelintime+subscribe@googlegroups.com



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